

**ACCU
2023**

MODIFIED CONDITION/DECISION COVERAGE IN GCC

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Topics

- ▶ Code coverage - overview and taxonomy
- ▶ Introduction to modified condition/decision coverage (MC/DC)
- ▶ Some example programs
- ▶ A (thorough) description of the algorithm in gcc (notation warning)

By the end you will ...

- ▶ Be familiar with {line, branch, condition} coverage
- ▶ Know about different kinds of MC/DC
- ▶ Understand masked conditions
- ▶ Be able to measure MC/DC with gcc and gcov
- ▶ Have seen some cool maths

There will also be some nuggets, words of wisdom, from smart people

Code coverage

Code coverage is a **collection of metrics** for different properties of your **test suite**. Programs are **instrumented** to record **run-time** information. This is sensitive to inputs and results are usually aggregated over **multiple runs**.

Nugget

Any coverage metric should not be a **goal**, but a measurement of how well the **requirement tests** exercise the structure of the program.

Hayhurst (2001): A Practical Tutorial on Modified Condition/ Decision Coverage.

Silly example:

```
bool maybe_record(double a) {  
    if (round(a) >= a) {  
        update_counter();  
        return true;  
    } else {  
        return false;  
    }  
}  
  
maybe_record(0.6); // should round up  
maybe_record(6.0); // should not round up
```

```
2:      9:bool maybe_round(double x) {
2:      10:      if (round(x) >= x) {
2:      11:          update_counter();
2:      12:          return true;
-:      13:      } else {
#####: 14:          return false;
-:      15:      }
-:      16:}
-:      17:
1:      18:int main() {
1:      19:      maybe_round(0.6);
1:      20:      maybe_round(6.0);
1:      21:}
```

Oops, else-block not exercised.

A taxonomy of coverage metrics

Line/Statement	Has every line of the source been executed?
Branch/Decision	Has every control flow structure been evaluated to <i>both</i> true and false?
Condition	Has every boolean sub-expression been evaluated to <i>both</i> true and false?

A taxonomy of coverage metrics

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Even line coverage can require a lot of effort

Line/Statement coverage

Has every **line** of the source been executed?

```
int badadder(int x, int y) {  
    int tmp = x;  
    tmp = tmp + (y - 5);  
    return tmp;  
    tmp += 5;    // dead as a do-do  
}
```

Obviously cannot achieve 100% line coverage.

Line/Statement coverage

Has every **line** of the source been executed?

```
int fn(T* x) {  
    if (precondition1(x))  
        return -1;  
    if (precondition2(x))  
        return -1;  
    work(x);  
    return 0;  
}
```

Branch/Decision coverage

Has every **control flow** structure been evaluated to *both* true and false?

```
if (x) {  
    // at least once  
    first();  
} else {  
    // at least once  
    second();  
}
```

Branch/Decision coverage

Has every **control flow** structure been evaluated to *both* true and false?

```
if (x) {  
    // at least once  
    first();  
} else {  
    // at least once  
    second();  
}
```

How is this different from statement coverage?

```
if (x) {  
    first();  
}  
next();
```

When x is true this has 100% statement coverage and 50% decision coverage.

```
if (always_true()) {  
    first();  
}  
next();
```


every **control flow** [...]

for and while are ifs with fake beards

```
while (cond) {  
    f(); g();  
}  
reset();  
loop:  
    if (!cond) goto endloop;  
    f(); g();  
    goto loop;  
endloop: ;
```

every control flow [...]

for and while are ifs with fake beards

```
while (cond) {
    f(); g();
}
reset();
loop:
    if (!cond) goto endloop;
    f(); g();
    goto loop;
endloop: ;
```

```
1:    6:int main() {
2:    7:    while (cond) {
branch 0 taken 50%
branch 1 taken 50% (fallthrough)
1:    8:        f(); g();
-:    9:    }
1:   10:    reset();
2:   11:loop:
2:   12:    if (!cond) goto endloop;
branch 0 taken 50% (fallthrough)
branch 1 taken 50%
1:   13:    f(); g();
1:   14:    goto loop;
1:   15:endloop: ;
-:   16:}
```

Condition coverage

Has every **boolean sub-expression** been evaluated to *both* true and false?

```
if (x && y) {  
    both();  
}
```

x	y	%
0	0	25
1	0	75
1	1	100

More statement vs decision coverage

```
while (accidentally_always_true()) {  
    f();  
    if (g()) break;  
    h();  
}
```

More statement vs decision coverage

```
while (accidentally_always_true()) {  
    f();  
    if (g()) break;  
    h();  
}
```

The **loop** always terminates, but only because of the **break**. Could have 100% statement coverage, but not decision coverage.

More condition coverage

```
if (x && accidentally_always_true(y)) {  
    both();  
} else {  
    htob();  
}
```

```
fn(0, 0); // 25%  
fn(1, 0); // 75%  
fn(1, 1); // 100%
```

Condition coverage is clearly insufficient.

```
$ gcov -b program
3:      5: void fn(int x, int y) {
3:      6:      if (x && accidentally_always_true(y)) {
branch 0 taken 67% (fallthrough)
branch 1 taken 33%
branch 3 taken 100% (fallthrough)
branch 4 taken 0%
2:      7:          both();
-:      8:      } else {
1:      9:          htob();
-:     10:      }
3:     11: }
-:     12:
1:     13: int main() {
1:     14:     fn(0, 0);
1:     15:     fn(1, 0);
1:     16:     fn(1, 1);
-:     17: }
```

```
struct C {  
    C() { ... }  
    C(const C&) { ... }  
    C(C&&) { ... }  
    C& operator = (const C&) { ... }  
    C& operator = (C&&) { ... }  
};
```



```
struct C {  
    C() { ... }  
    C(const C&) { ... }  
    C(C&&)      { ... }  
    C& operator = (const C&) { ... }  
    C& operator = (C&&)      { ... }  
};
```

Does your test suite *actually* call the move constructor?

Nugget

C++ is the only language I know that lets you specify a custom copy function and then do its best to not call it.

Tony van Eerd

gcc

gcc emits **.gcno** files (source annotation) and runs create or update **.gcta** files (counters)

Quick start

- ▶ Build with `gcc --coverage`
- ▶ Run program, test suite
- ▶ Generate report with `gcov <program>` or `gcov <source>`
- ▶ Read the manual

General advice

- ▶ Icov is very useful
- ▶ Results (particularly source mapping) only reliable without optimizations
- ▶ Apply common sense and good engineering

Modified condition/decision coverage

- ▶ How is it different from condition coverage?
- ▶ Why even care?

Why even care?



- ▶ DO-178B/C (Level A)
- ▶ ISO26262 (ASIL D)

Why even care?

- ▶ It is a good metric
- ▶ Can detect unintended data dependence
- ▶ Can detect classes of bad expressions
- ▶ Requires testing more interactions in your program
- ▶ Drives robustness

The problem with decision coverage:

```
if ((a && b) || c) {  
    //  
} else {  
    //  
}
```

a	b	c	
F	F	F	F
F	F	T	T
F	T	F	F
F	T	T	T
T	F	F	F
T	F	T	T
T	T	F	T
T	T	T	T

Metric not very sensitive to the conditions and their interaction, only need two tests for three parameters.

Modified condition/decision coverage satisfied if:

- ▶ every entry and exit point has been invoked
- ▶ every basic condition has taken on all possible outcomes
- ▶ each basic condition has been shown to independently affect the decision's outcome

```
if ((a && b) || c) {  
    //  
} else {  
    //  
}
```

- ▶ every entry and exit point has been invoked

Branch coverage

a	b	c	
F	F	F	F
F	F	T	T
F	T	F	F
F	T	T	T
T	F	F	F
T	F	T	T
T	T	F	T
T	T	T	T

```
if ((a && b) || c) {  
    //  
} else {  
    //  
}
```

- ▶ every basic condition has taken on all possible outcomes

Condition coverage

a	b	c	
F	F	F	F
F	F	T	T
F	T	F	F
F	T	T	T
T	F	F	F
T	F	T	T
T	T	F	T
T	T	T	T

```
if ((a && b) || c) {  
    //  
} else {  
    //  
}
```

- ▶ each basic condition has been shown to *independently* affect the decision's outcome

Modified condition/decision coverage

a	b	c	
F	F	F	F
F	F	T	T
F	T	F	F
F	T	T	T
T	F	F	F
T	F	T	T
T	T	F	T
T	T	T	T

- ▶ Testing all 2^N inputs would not reliably catch more defects
- ▶ $N + 1$ test cases is sufficient (for coverage)

The problem with MC/DC

- ▶ Only tests implementation, not the spec
- ▶ Possible to cheat
- ▶ Needs many test cases in maybe uninteresting places
- ▶ *Awful* to determine without tooling
- ▶ Can be expensive and at odds with fuzzing
- ▶ Can lead to *Metric Driven Development* (MDD)

Nugget

This is because MC/DC testing discourages defensive code with unreachable branches, but without defensive code, a fuzzer is more likely to find a path that causes problems.

Nugget

MC/DC testing seems to work well for building code that is robust during normal use, whereas fuzz testing is good for building code that is robust against malicious attack.

<https://www.sqlite.org/testing.html>

A taxonomy of coverage metrics

Line/Statement

Has every **line** of the source been executed?

Branch/Decision

Has every **control flow** structure been evaluated to *both* true and false?

Condition

Has every **boolean sub-expression** been evaluated to *both* true and false?

Modified Condition/Decision coverage

Has every **control flow** structure been evaluated to *both* true and false **and** every condition been shown to affect the decision outcome **independently**?

Unique-cause MC/DC

Only **one** condition may change between a test vector pair, and the resulting decision must be different for the two test vectors.

Unique-cause MC/DC

Only **one** condition may change between a test vector pair, and the resulting decision must be different for the two test vectors.

```
if ((a && b) || (c && d))
```

a	b	c	d	
0	1	0	1	0
1	1	0	1	1
1	0	0	1	0
1	0	1	1	1
1	0	1	0	0

- ▶ Need $N + 1$ *specific* test cases to achieve coverage.
- ▶ No coverage set if **strongly coupled conditions**.

Masking MC/DC

Only **one** condition having an **influence** on the outcome may change between a test vector pair.

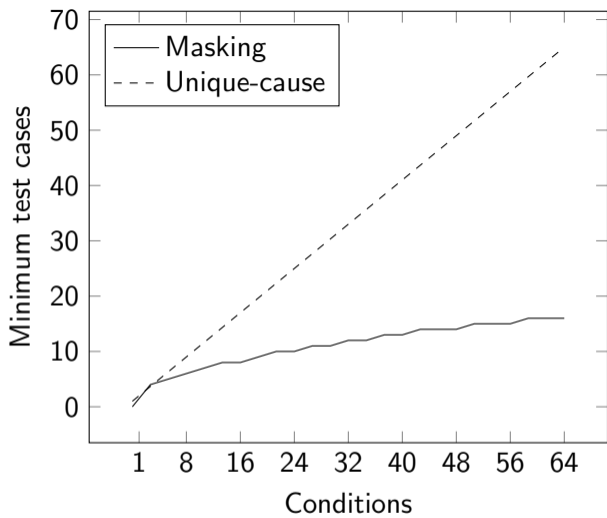
Masking MC/DC

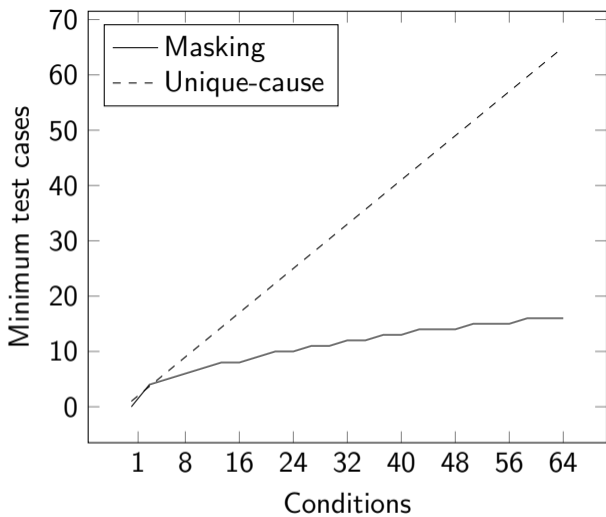
Only **one** condition having an **influence** on the outcome may change between a test vector pair.

```
if ((a && b) || (c && d))
```

a	b	c	d	
0	1	0	1	0
1	1	0	1	1
1	0	1	1	1
1	0	1	0	0

- ▶ Need $\lceil 2\sqrt{N} \rceil$ test cases to achieve coverage.
- ▶ Multiple test vector sets to choose from, some tests may map better to the requirements.





$$N + 1 \approx \lceil 2\sqrt{N} \rceil \text{ for small } N$$

Nugget

Masking MC/DC generally require fewer test cases than unique-cause MC/DC, but is as good at detecting errors.

Chilenski (2001): An Investigation of Three Forms of the Modified Condition Decision Coverage (MCDC) Criterion.

I wrote a patch for gcc

```
$ git log -n 1 --format=short --shortstat  
Author: Jørgen Kvalsvik <jorgen.kvalsvik@woven-planet.global>
```

```
    Add condition coverage profiling
```

```
21 files changed, 2952 insertions(+), 27 deletions(-)
```

```
gcc/tree-profile.cc | +978
```

Quick start

```
gcc --coverage -fprofile-conditions
```

Demo

```
$ gcc --coverage -fprofile-conditions
    demo.c -o demo
$ ./demo 0 0 0
$ ./demo 0 0 1
$ ./demo 1 0 0
$ gcov --conditions demo
$ cat demo.c.gcov
```

```
    if ((a && b) || c) {
condition outcomes covered 4/6
condition  0 not covered (true)
condition  1 not covered (true)
```

Question

Why is `a = 1` not covered?

Note

This section covers **masking** MC/DC

Requirement

Each basic condition has been shown to **independently** affect the decision's outcome.

Definition

A condition **independently** affects the outcome if changing it while keeping the **other values constant** changes the outcome.

```
if ((a && b) || c) {  
    //  
} else {  
    //  
}
```

a	b	c	
F	F	F	F
F	F	T	T
F	T	F	F
F	T	T	T
T	F	F	F
T	F	T	T
T	T	F	T
T	T	T	T

Observation

Changing a does not change the decision

This effect is called *masking*

▶ * || true

▶ * && false

Commutation

Reversing a boolean expression does not change its truth table

$$(P \wedge Q) \equiv (Q \wedge P)$$

$$(P \vee Q) \equiv (Q \vee P)$$

Observation

Masked conditions are *short circuited* in the reversed expression

(a && b)				c
a	b	c		
F	*	F		F
F	*	T		T
F	*	F		F
F	*	T		T
T	F	F		F
T	F	T		T
T	T	*		T
T	T	*		T

c		(b && a)	
c	b	a	
F	F	-	F
F	F	-	F
F	T	F	F
F	T	T	T
T	-	-	T
T	-	-	T
T	-	-	T
T	-	-	T

Short circuiting for the expression * and the reverse -

(a && b)				c
a	b	c		
F	*	F		F
F	*	T		T
F	*	F		F
F	*	T		T
T	F	F		F
T	F	T		T
T	T	*		T
T	T	*		T

c		(b && a)	
c	b	a	
F	F	-	F
T	-	-	T
F	T	F	F
T	-	-	T
F	F	-	F
T	-	-	T
F	T	T	T
T	-	-	T

(a && b)				c
a	b	c		
F	*	F		F
-	-	T		T
F	*	F		F
-	-	T		T
T	F	F		F
-	-	T		T
T	T	*		T
T	T	*		T

Note

Row order in $c \ || \ (b \ \&\& \ a)$ changed

$(a \ \&\& \ b) \ || \ c$

	a	b	c	
1	F	*	F	F
2	-	-	T	T
3	F	*	F	F
4	-	-	T	T
5	T	F	F	F
6	-	-	T	T
7	T	T	*	T
8	T	T	*	T

$$a = \{5, 7, 8\}$$

$$\neg a = \{1, 3\}$$

$$b = \{7, 8\}$$

$$\neg b = \{5\}$$

$$c = \{2, 4, 6\}$$

$$\neg c = \{1, 3, 5\}$$

Test sets for cases for masking MC/DC.

$(a \ \&\& \ b) \ || \ c$

	a	b	c	
1	F	*	F	F
2	-	-	T	T
3	F	*	F	F
4	-	-	T	T
5	T	F	F	F
6	-	-	T	T
7	T	T	*	T
8	T	T	*	T

- $a = \{5, 7, 8\}$
- $\neg a = \{1, 3\}$
- $b = \{7, 8\}$
- $\neg b = \{5\}$
- $c = \{2, 4, 6\}$
- $\neg c = \{1, 3, 5\}$

Test sets for cases for masking MC/DC.

$(a \ \&\& \ b) \ || \ c$

	a	b	c	
1	F	*	F	F
2	-	-	T	T
3	F	*	F	F
4	-	-	T	T
5	T	F	F	F
6	-	-	T	T
7	T	T	*	T
8	T	T	*	T

-
-

$$a = \{5, 7, 8\}$$
$$\neg a = \{1, 3\}$$
$$b = \{7, 8\}$$
$$\neg b = \{5\}$$
$$c = \{2, 4, 6\}$$
$$\neg c = \{1, 3, 5\}$$

Test sets for cases for masking MC/DC.

$(a \ \&\& \ b) \ || \ c$

	a	b	c	
1	F	*	F	F
2	-	-	T	T
3	F	*	F	F
4	-	-	T	T
5	T	F	F	F
6	-	-	T	T
7	T	T	*	T
8	T	T	*	T

$$a = \{5, 7, 8\}$$

$$\neg a = \{1, 3\}$$

$$b = \{7, 8\}$$

$$\neg b = \{5\}$$

$$c = \{2, 4, 6\}$$

$$\neg c = \{1, 3, 5\}$$

-
-

Test sets for cases for masking MC/DC.

$(a \ \&\& \ b) \ || \ c$

	a	b	c	
1	F	*	F	F
2	-	-	T	T
3	F	*	F	F
4	-	-	T	T
5	T	F	F	F
6	-	-	T	T
7	T	T	*	T
8	T	T	*	T

$$a = \{5, 7, 8\}$$
$$\neg a = \{1, 3\}$$
$$b = \{7, 8\}$$
$$\neg b = \{5\}$$
$$c = \{2, 4, 6\}$$
$$\neg c = \{1, 3, 5\}$$

Test sets for cases for masking MC/DC.

Detecting errors

Specification (a && b) || c

Implementation (a && !c) || c

Masking table

a	b	c	
F	*	F	F
-	-	T	T
F	*	F	F
-	-	T	T
T	F	F	F
-	-	T	T
T	T	*	T
T	T	*	T

(a && !c) || c

a	!c	c	
F	*	F	F
-	-	T	T
F	*	F	F
-	-	T	T
T	T	*	T
-	-	T	T
T	T	*	T
T	T	*	T

Masking table

a	b	c	
F	*	F	F
-	-	T	T
F	*	F	F
-	-	T	T
T	F	F	F
-	-	T	T
T	T	*	T
T	T	*	T

(a && !c) || c

a	!c	c	
F	*	F	F
-	-	T	T
F	*	F	F
-	-	T	T
T	T	*	T
-	-	T	T
T	T	*	T
T	T	*	T

Note

Some strong coupled conditions cannot be detected by masking MC/DC

(a && b) || (a && c)

a	b	a	c	
0	*	0	*	0
0	*	0	*	0
-	0	-	0	0
-	0	1	1	1
0	*	-	0	0
0	*	0	*	0
1	1	*	*	1
1	1	*	*	1

Full unique-cause coverage is not possible
(a repeated)

Cheating MC/DC

```
if ((a && b) || c) {  
    //  
} else {  
    //  
}
```

a	b	c	
F	F	F	F
F	F	T	T
F	T	F	F
F	T	T	T
T	F	F	F
T	F	T	T
T	T	F	T
T	T	T	T

```
int ab = a && b;  
if (ab || c) {  
    //  
} else {  
    //  
}
```

ab	c
F	F
F	T
T	F
T	T

Programs

If computers had blood, we would be considered butchers

gcc does **control flow graph** analysis for coverage

gcc does **control flow graph** analysis for coverage

```
if (a && b && c)
    x = 1;
```

```
if (a)
    if (b)
        if (c)
            x = 1;
```

gcc does **control flow graph** analysis for coverage

```
if (a && b && c)
    x = 1;
```

```
if (a)
    if (b)
        if (c)
            x = 1;
```

```
#####: 2:    if (a && b && c)
condition outcomes covered 6/6
```

```
#####: 3:        x = 1;
```

```
#####: 2:    if (a)
```

```
#####: 3:        if (b)
```

```
#####: 4:            if (c)
```

```
#####: 5:                x = 1;
```

```
condition outcomes covered 6/6
```

Rust #1

```
fn f(a: bool, b: bool, c: bool) -> bool {  
    a || (b && c)  
}
```

```
fn main() {  
    f(true, true, false);  
    f(false, true, false);  
}
```

Rust #1

```
$ gccrs --coverage -fprofile-conditions prog.rs -o prog \
    -frust-incomplete-and-experimental-compiler-do-not-use
$ ./prog
$ gcov --conditions prog
File 'prog.rs'
Lines executed:100.00% of 5
Condition outcomes covered:50.00% of 6
Creating 'prog.rs.gcov'
```

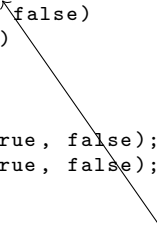
Rust #1

```
2:     1:fn f(a: bool, b: bool, c: bool) -> bool {
2:     2:     a || (b && c)
condition outcomes covered 3/6
condition 1 not covered (true false)
condition 2 not covered (true)
-:     3:}
-:     4:
1:     5:fn main() {
1:     6:     f(true,  true, false);
1:     7:     f(false, true, false);
-:     8:}
```

Rust #1

```
2:     1:fn f(a: bool, b: bool, c: bool) -> bool {
2:     2:     a || (b && c)
condition outcomes covered 3/6
condition 1 not covered (true false)
condition 2 not covered (true)
-:     3:}
-:     4:
1:     5:fn main() {
1:     6:     f(true, true, false);
1:     7:     f(false, true, false);
-:     8:}
```

Summary



Rust #1

```
2:     1:fn f(a: bool, b: bool, c: bool) -> bool {
2:     2:     a || (b && c)
condition outcomes covered 3/6
condition 1 not covered (true false)
condition 2 not covered (true)
-:     3:}
-:     4:
1:     5:fn main() {
1:     6:     f(true, true, false);
1:     7:     f(false, true, false);
-:     8:}
```

Condition index



Rust #1

```
2:     1:fn f(a: bool, b: bool, c: bool) -> bool {
2:     2:     a || (b && c)
condition outcomes covered 3/6
condition 1 not covered (true false)
condition 2 not covered (true)
-:     3:}
-:     4:
1:     5:fn main() {
1:     6:     f(true, true, false);
1:     7:     f(false, true, false);
-:     8:}
```

Quiet if fully covered

Rust #1

```
2:     1:fn f(a: bool, b: bool, c: bool) -> bool {
2:     2:     a || (b && c)
condition outcomes covered 3/6
condition 1 not covered (true false)
condition 2 not covered (true)
-:     3:}
-:     4:
1:     5:fn main() {
1:     6:     f(true, true, false);
1:     7:     f(false, true, false);
-:     8:}
```

Conditions **not** shown to be independent

Rust #2

```
fn loops(init: i32) -> i32 {
    let mut i = init;
    let mut x = 0;
    while true {
        x *= i;
        i += 1;
        if i > 5 { break }
    }
    while i < 20 {
        x -= i;
        i *= 2;
    }
    x
}

fn main() {
    loops(0);
    loops(5);
}
```

Rust #2

```
2:     1:fn loops(init: i32) -> i32 {
2:     2:     let mut i = init;
2:     3:     let mut x = 0;
5:     4:     while true {
7*:    5:         x *= i;
condition outcomes covered 1/2
condition 0 not covered (true)
7*:    6:         i += 1;
condition outcomes covered 1/2
condition 0 not covered (true)
7:     7:         if i > 5 { break }
condition outcomes covered 2/2
-:     8:     }
6:     9:     while i < 20 {
condition outcomes covered 2/2
4*:   10:         x -= i;
condition outcomes covered 1/2
condition 0 not covered (true)
4*:   11:         i *= 2;
condition outcomes covered 1/2
condition 0 not covered (true)
-:   12:     }
2:   13:     x
-:   14: }
```

C++ #1

```
class C {
public:
    explicit C(int c) noexcept (true) : v(c) {}
    bool operator < (const C& o) const noexcept (true) {
        return this->v < o.v;
    }

private:
    int v;
};

int main() {
    C one(1), two(2);
    int three = 3, four = 4;
    int x = 0;
    if (one < two && four < three)
        x = 1;
}
```

C++ #1

```
1:      9:int main() {
1:     10:      C one(1), two(2);
1:     11:      int three(3), four(4);
1:     12:      int x = 0;
1*:    13:      if (one < two && four < three)
condition outcomes covered 1/4
condition 0 not covered (true false)
condition 1 not covered (true)
condition outcomes covered 1/2
condition 0 not covered (true)
#####:    14:          x = 1;
1:     15:}
```

C++ #1

```
1:      9:int main() {
1:     10:      C one(1), two(2);
1:     11:      int three(3), four(4);
1:     12:      int x = 0;
1*:    13:      if (one < two && four < three)
condition outcomes covered 1/4
condition 0 not covered (true false)
condition 1 not covered (true)
condition outcomes covered 1/2
condition 0 not covered (true)
#####:    14:          x = 1;
1:     15:}
```

gcc uses a temporary for the if

D #1

```
1:    3: void main()
-:    4: {
1:    5:     stdin
-:    6:     .byLineCopy
-:    7:     .array
3:    8:     .sort!((a, b) => a > b)
1:    9:     .each!writeln;
-:   10: }
```


D #1

```
1:      3: void main()
-:      4: {
1:      5:     stdin
-:      6:         .byLineCopy
-:      7:         .array
3:      8:         .sort!((a, b) => a > b)
1:      9:         .each!writeln;
-:     10: }
```

string.d.gcov:

```
-: 251:     {
-: 252:         import core.stdc.string : memcmp;
-: 253:
5: 254:         const ret = memcmp( s1.ptr, s2.ptr, len );
5: 255:         if ( ret )
condition outcomes covered 1/2
condition 0 not covered (true)
#####: 256:             return ret;
-: 257:     }
5: 258:     return (s1.length > s2.length) - (s1.length < s2.length);
```

C #1

```
2:    1:int lt(int x, int y) {
2:    2:    return x < y;
-:    3:}
-:    4:
1:    5:int main() {
1:    6:    int one = 1, two = 2;
1:    7:    int three = 3, four = 4;
1:    8:    int x = 0;
1:    9:    if (lt(one, two) && lt(four, three))
condition outcomes covered 1/4
condition 0 not covered (true false)
condition 1 not covered (true)
#####: 10:    x = 1;
-:    11:}
```

C #2

```
1:      1:int main() {
1:      2:      int one = 1, two = 2;
1:      3:      int three = 3, four = 4;
1:      4:      int x = 0;
1*:     5:      int v = one < two && three < four;
condition outcomes covered 2/4
condition 0 not covered (false)
condition 1 not covered (false)
1:      6:      if (v)
condition outcomes covered 1/2
condition 0 not covered (false)
1:      7:          x = 1;
-:      8:      else
#####:  9:          x = -1;
-:     10:}
```

C #3

```
1:    1:int ternary(int a, int b) {
1*:    2:    int x = (a || b) ? f() : g();
condition outcomes covered 1/4
condition 0 not covered (false)
condition 1 not covered (true false)
-:    3:}
```

C #4

```
1:      1:int main() {
1:      2:      int a = 0, b = 3, c = 2;
1:      3:      int x = 0;
1*:     4:      if ((a && b) || (c && a))
condition outcomes covered 2/8
condition 0 not covered (true)
condition 1 not covered (true false)
condition 2 not covered (true false)
condition 3 not covered (true)
#####:  5:          x = 1;
```

Current status

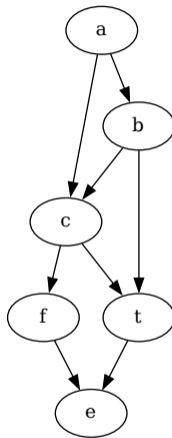
- ▶ Condition profiling is currently **pending review**
- ▶ Inferring conditionals from the CFG is **accurate**, but sometimes surprising
- ▶ Approach is sensitive to **frontend decisions**
- ▶ Reports can be unwieldy; see **lcov**
- ▶ No integration with build systems and testing frameworks

Algorithm


```
if ((a && b) || c) {  
    // t  
} else {  
    // f  
}  
// e
```

```
_a:  
    if (a) goto _b  
    else goto _c  
_b:  
    if (b) goto _t  
    else goto _c  
_c:  
    if (c) goto _t  
    else goto _f  
_t:  
    goto _e  
_f:  
    goto _e  
_e:
```

```
if ((a && b) || c) {  
    // t  
} else {  
    // f  
}  
// e
```

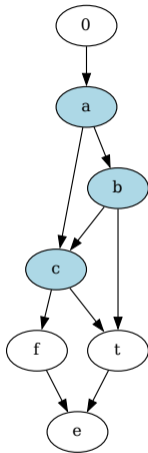


Control flow graph

- ▶ Directed graph
- ▶ Nodes are an uninterruptible sequence of instructions
- ▶ Edges are next possible paths of execution
- ▶ Edges are labelled fallthrough, true/false (conditional), complex
- ▶ Fallthrough and conditional are mutually exclusive

Act I: Inferring decisions

```
if ((a && b) || c) {  
    // t  
} else {  
    // f  
}  
// e
```



Observation

$$\bigcup \{ Succ(v) \mid v \in B \} = N[B]$$

$$N[B] = B \cup O_B$$

B is a decision (boolean expression)

O_B is the *outcome* of B

$N(B)$ is the *open neighborhood* of B

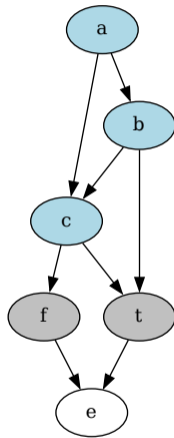
$N[B]$ is the *closed neighborhood* of B

uninterruptible

```
if ((a && b) || c) {  
} else {  
} outcome
```

outcome

$$\bigcup \{ Succ(v) \mid v \in B \}$$



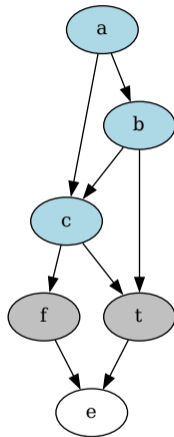
```

uninterruptible
├── if ((a && b) || c) {
│   └── } else {
│       └── outcome
│           └── }
└── }

```

$$E(B) = \{(u, v) \in E \mid u \in B, v \in N[B]\}$$

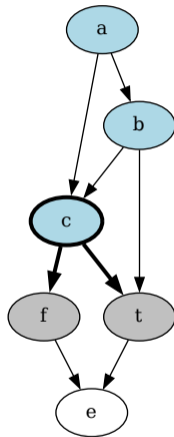
All edges in $E(B)$ are conditional

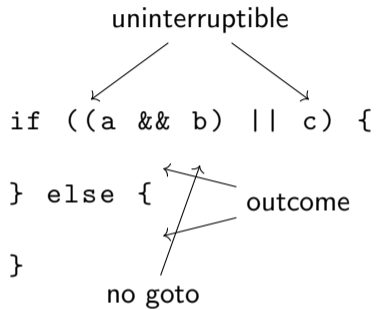


uninterruptible

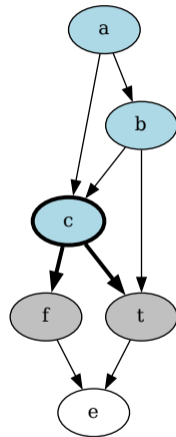
```
if ((a && b) || c) {  
} else {  
} outcome
```

$$\text{Succ}(B_\Omega) = O_B$$



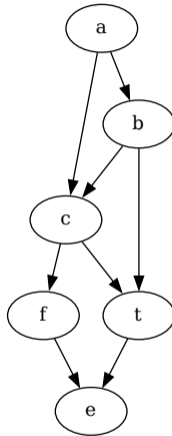


Can not goto to/from the middle of an *expression*

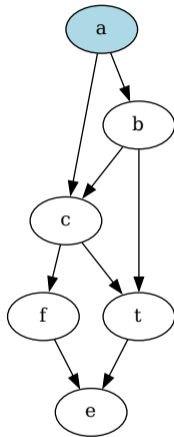


Reachable-by-condition-edge (BFS)

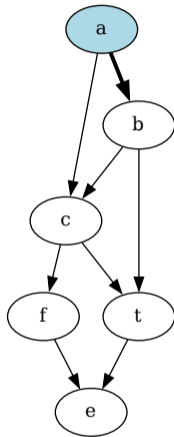
```
if ((a && b) || c) {  
    // t  
} else {  
    // f  
}
```



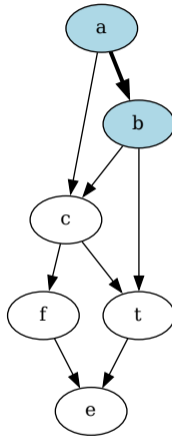
```
if ((a && b) || c) {  
    // t  
} else {  
    // f  
}
```



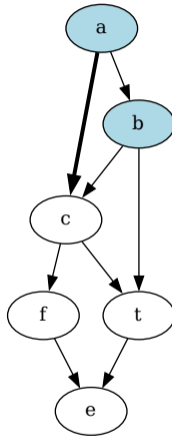
```
if ((a && b) || c) {  
    // t  
} else {  
    // f  
}
```



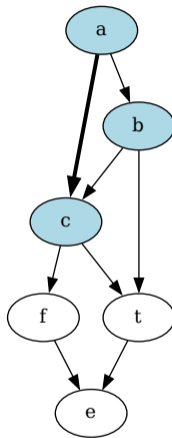
```
if ((a && b) || c) {  
    // t  
} else {  
    // f  
}
```



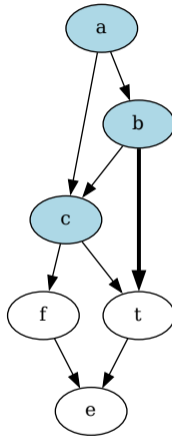
```
if ((a && b) || c) {  
    // t  
} else {  
    // f  
}
```



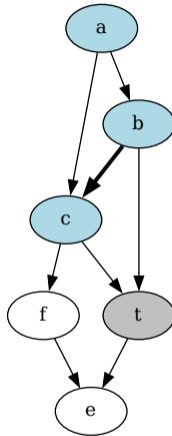

```
if ((a && b) || c) {  
    // t  
} else {  
    // f  
}
```



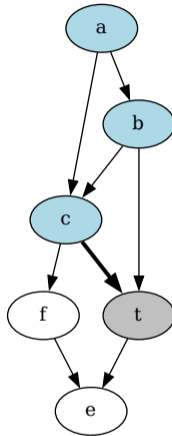
```
if ((a && b) || c) {  
    // t  
} else {  
    // f  
}
```



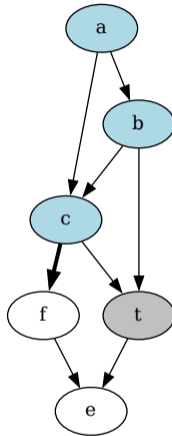
```
if ((a && b) || c) {  
    // t  
} else {  
    // f  
}
```



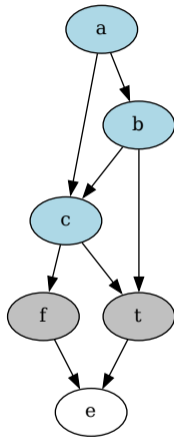
```
if ((a && b) || c) {  
    // t  
} else {  
    // f  
}
```



```
if ((a && b) || c) {  
    // t  
} else {  
    // f  
}
```



```
if ((a && b) || c) {  
    // t  
} else {  
    // f  
}
```

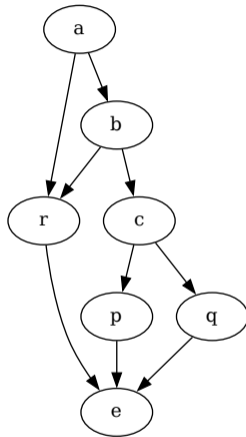


```

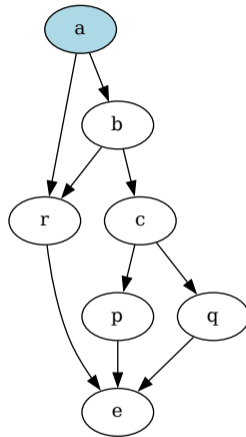
1: function REACH( $v_0, v_p$ )
2:    $R \leftarrow \{ \}$ 
3:    $Q \leftarrow$  QUEUE( $v_0$ )
4:   repeat
5:      $v \leftarrow$  POP( $Q$ )
6:     for  $s$  in Succs( $v$ ) do
7:       skip if  $s \in R$ 
8:       skip if IS-SAME( $s, v_p$ )
9:       skip if IS-BACK-EDGE( $v, s$ )
10:      skip if  $\neg$  DOMINATED-BY( $s, v_0$ )
11:      skip if  $\neg$  IS-CONDITIONAL( $s$ )
12:      ENQUEUE( $Q, s$ )
13:      ADD( $R, s$ )
14:   until EMPTY( $Q$ )
15:   return  $R$ 

```

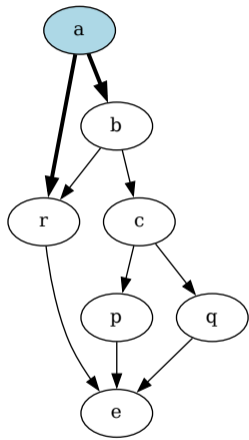
```
if (a && b) {  
    if (c) {  
        // p  
    } else {  
        // q  
    }  
}  
else {  
    // r  
}
```



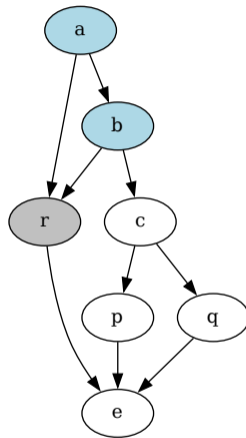

```
if (a && b) {  
    if (c) {  
        // p  
    } else {  
        // q  
    }  
}  
else {  
    // r  
}
```



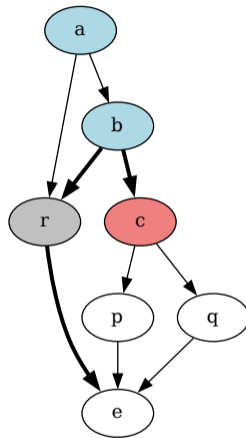
```
if (a && b) {  
    if (c) {  
        // p  
    } else {  
        // q  
    }  
} else {  
    // r  
}
```



```
if (a && b) {  
    if (c) {  
        // p  
    } else {  
        // q  
    }  
} else {  
    // r  
}
```



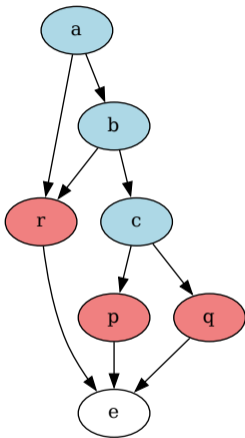
```
if (a && b) {  
    if (c) {  
        // p  
    } else {  
        // q  
    }  
}  
else {  
    // r  
}
```



```
if (a && b) {  
  if (c) {  
    // p  
  } else {  
    // q  
  }  
} else {  
  // r  
}
```

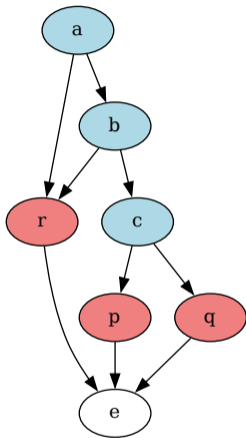
$$C = (G, G')$$

$$\begin{aligned}\forall e \in E(G) \bullet \text{cond}(e) \\ \Rightarrow O_B \subset N[G] \\ \Rightarrow B \subseteq G\end{aligned}$$



```
if (a && b) {  
    if (c) {  
        // p  
    } else {  
        // q  
    }  
}  
else {  
    // r  
}
```

No path from **then** to **else**

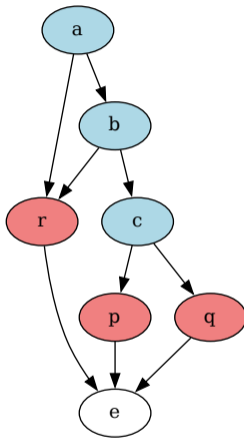


```
if (a && b) {  
  if (c) {  
    // p  
  } else {  
    // q  
  }  
} else {  
  // r  
}
```

$\forall v \in \text{then}(B) \bullet B \subset A(v)$

$\forall v \in \text{else}(B) \bullet B \subset A(v)$

where $A(v)$ are the ancestors of v

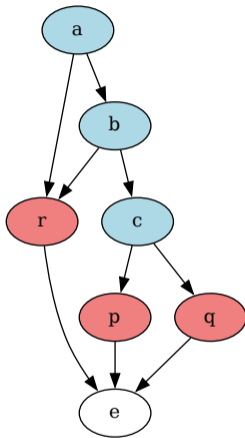


```

if (a && b) {
  if (c) {
    // p
  } else {
    // q
  }
} else {
  // r
}

```

outcome

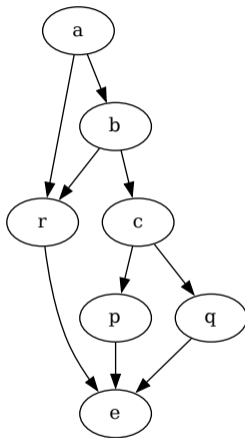


$\forall v \in \text{then}(B) \bullet B \subset A(v)$

$\forall v \in \text{else}(B) \bullet B \subset A(v)$

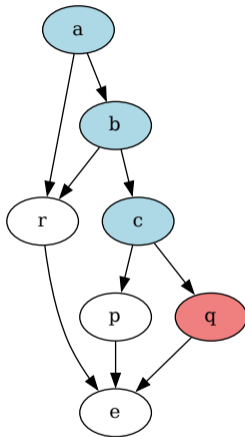
where $A(v)$ are the ancestors of v


```
if (a && b) {  
    if (c) // p  
    else   // q  
} else {  
    // r  
}
```



```
if (a && b) {  
    if (c) // p  
    else   // q  
} else {  
    // r  
}
```

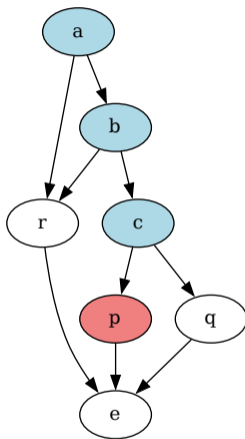
$$A(q) = \{c, b, a\}$$



```
if (a && b) {  
    if (c) // p  
    else   // q  
} else {  
    // r  
}
```

$A(q) = \{c, b, a\}$

$A(p) = \{c, b, a\}$

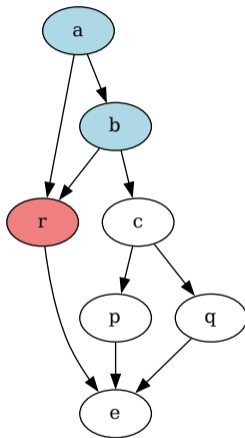


```
if (a && b) {  
    if (c) // p  
    else   // q  
} else {  
    // r  
}
```

$A(q) = \{c, b, a\}$

$A(p) = \{c, b, a\}$

$A(r) = \{b, a\}$



```
if (a && b) {  
    if (c) // p  
    else   // q  
} else {  
    // r  
}
```

$$A(q) = \{c, b, a\}$$

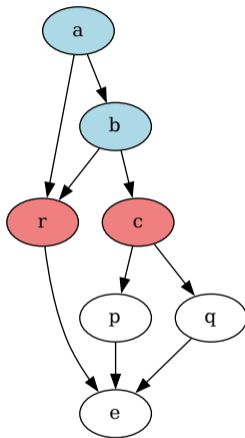
$$A(p) = \{c, b, a\}$$

$$A(r) = \{b, a\}$$

$$B = \bigcap \{A(q), A(p), A(r)\}$$

$$= \{a, b\}$$

$$O_B = \{r, c\}$$



Problem

BFS needs to start at left-most term B_0

Solution

Process program depth-first, mark when processed

- ▶ If v is fallthrough \Rightarrow mark and continue
- ▶ If v is conditional \Rightarrow if B_0 and B are marked
- ▶ If v is marked \Rightarrow continue

Note

May lead to expressions being processed "out of order"

```
1: function FIND-DECISION( $v_0, v_p$ )
2:    $G \leftarrow$  REACH( $v_0, v_p$ )
3:   if  $|G| = 1$  then
4:     return  $G$ 
5:    $B \leftarrow G$ 
6:   for  $n$  in  $N(G)$  do
7:      $P \leftarrow \{ \}$ 
8:     for  $v$  in  $Preds(n)$  do
9:        $P \leftarrow P \cup A_G(v)$ 
10:     $B \leftarrow B \cap P$ 
11:  return  $B$ 
```

```
cond_reachable_from (p, post, reachable, G);
if (G.length () == 1) {
    out.safe_push (p);
    return;
}

neighborhood (G, reachable, NG);
bitmap_copy (expr, reachable);

for (const basic_block neighbor : NG) {
    bitmap_clear (ancestors);
    for (edge e : neighbor->preds)
        ancestors_of (e->src, p, reachable, ancestors);
    bitmap_and (expr, expr, ancestors);
}

for (const basic_block b : G)
    if (bitmap_bit_p (expr, b->index))
        out.safe_push (b);
out.sort (cmp_index_map, &ctx.index_map);
```



```
1: function FIND-ALL-DECISIONS( $G$ )
2:    $R \leftarrow \{ \}$ 
3:   for  $v_0 \leftarrow$  DEPTH-FIRST( $G$ ) do
4:     skip if MARKED( $v_0$ )
5:     if IS-CONDITIONAL( $v_0$ ) then
6:        $v_p \leftarrow$  GET-POST-DOMINATOR( $v_0$ )
7:        $B \leftarrow$  FIND-DECISION( $v_0, v_p$ )
8:       ADD( $R, B$ )
9:       MARK( $B$ )
10:    else
11:      MARK( $v_0$ )
12:   return  $R$ 
```

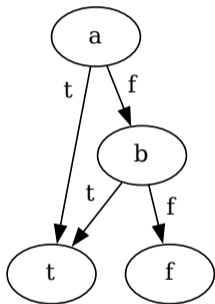
Act II: The masking vector

When masking happens

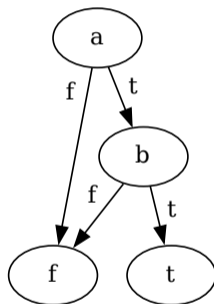
- * `||` true
- * `&&` false

Observation

Boolean expressions are isomorphic under the operator



$a \parallel b$



$a \&\& b$

Proposition

Boolean expressions are isomorphic under the operator

Proof

De Morgan's Laws

$$\neg(P \wedge Q) \equiv \neg P \vee \neg Q$$

$$\neg(P \vee Q) \equiv \neg P \wedge \neg Q$$

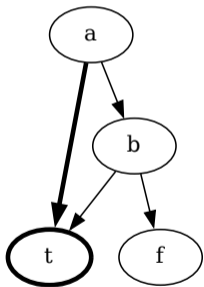
Implication

We don't need to know the operator, only the graph shape

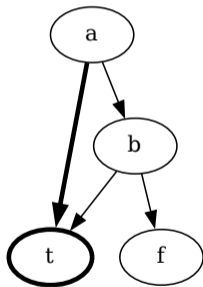
When masking happens (in CFG)

When a value c is changed (taking a different edge at v_c) and we still end in the same outcome node

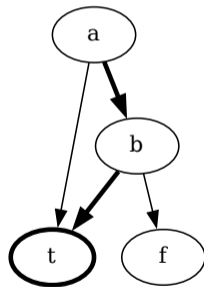
$f = a \parallel b$



f 1 0



f 1 1



f 0 1

Observation

Masking happens at nodes with *multiple* predecessors

Implication

Multiple predecessors means short circuiting edge

Implication

We know where to start searching

Association

$$P \wedge (Q \wedge R) \equiv (P \wedge Q) \wedge R$$

$$P \vee (Q \vee R) \equiv (P \vee Q) \vee R$$

Implication

We can re-write expressions to an *alternating* form

$$(A \vee B) \vee ((C \wedge D) \vee E)$$

$$A \vee B \vee (C \wedge D) \vee E$$

Observation

Masking propagates until the operator changes

$$A \wedge (B \vee C \vee D)$$

$D = t$ masks B, C , but not A

Subexpressions can mask

$$A \wedge (B \vee C)$$

$C = f$ masks A , but not B

$$F = B \vee C$$

$$A \wedge F$$

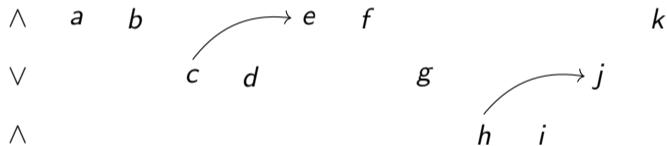
Observation

The *last term* S_Ω in a subexpression can short circuit the superexpression

$$a \wedge b \wedge (c \vee d) \wedge e \wedge f \wedge (g \vee (h \wedge i) \vee j) \wedge k$$

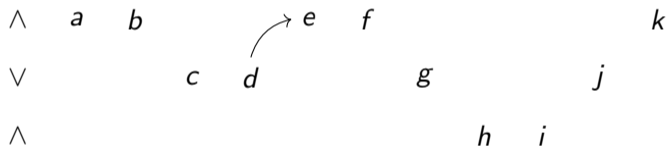
$$\begin{array}{ccccccccccc} \wedge & a & b & & & e & f & & & & k \\ \vee & & & c & d & & & g & & & j \\ \wedge & & & & & & & & h & i & \end{array}$$

$$a \wedge b \wedge (c \vee d) \wedge e \wedge f \wedge (g \vee (h \wedge i) \vee j) \wedge k$$



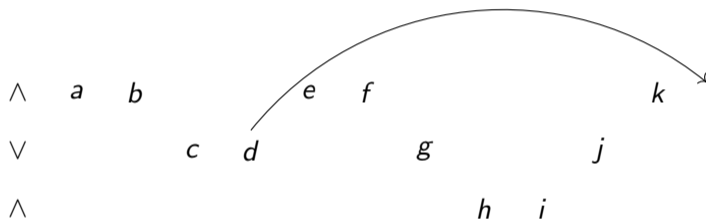
$c = \text{true}, h = \text{true}$

$$a \wedge b \wedge (c \vee d) \wedge e \wedge f \wedge (g \vee (h \wedge i) \vee j) \wedge k$$



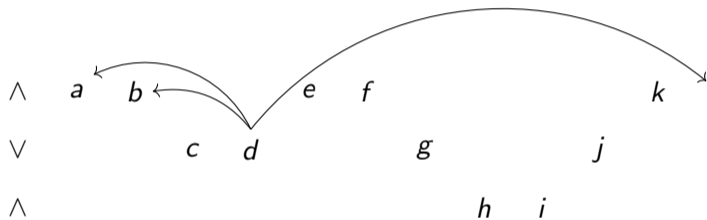
$d = true$

$$a \wedge b \wedge (c \vee d) \wedge e \wedge f \wedge (g \vee (h \wedge i) \vee j) \wedge k$$



$d = \text{false}$

$$a \wedge b \wedge (c \vee d) \wedge e \wedge f \wedge (g \vee (h \wedge i) \vee j) \wedge k$$



$$d = \text{false}$$

$$\text{Succ}(B_\Omega) = O_B$$

Observation

On evaluating a condition; either

- ▶ Short-circuit right operands
- ▶ Evaluate next operand

Implication

If one edge is a short circuiting edge, the other must be a masking edge

Problem

Given a pair of incoming edges, which is masking and which is short circuiting?

Proposition

An ordering $v_n < v_m$ if v_n is a left operand and v_m is a right operand in the same expression

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Solution

Topological sort

Given $\{v_n, v_m\} = \text{Preds}(v)$, $v_n < v_m$ then

$$v_n = S_\Omega$$

$$O_S = \text{Succ}(v_n)$$

where S is a subexpression of B ($S \subset B$)

Implication

When (v_m, v) is taken, S are masked

Remember

$$v_n, v_m = \text{Preds}(v)$$

$$v_n = S_\Omega$$

$$O_S = \text{Succ}(v_n)$$

$$N[B] = \bigcup \{ \text{Succ}(v) \mid v \in B \}$$

$$N(B) = O_B$$

Everything that applies to the superexpression B applies to the subexpression S

Problem

Given a node v with $|Preds(v)| \geq 2$, find the nodes masked when taking an edge to v

Intermediate problem

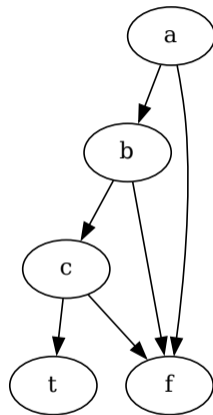
There can be more than one masking edge

Solution

$$\{ (v_n, v_m) \in Preds(v) \times Preds(v) \mid v_n < v_m \}$$

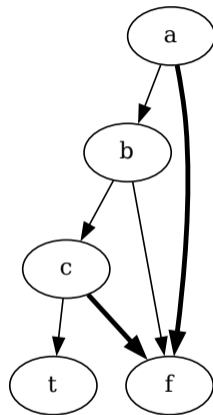
$$\{ (v_n, v_m) \in \text{Preds}(v)^2 \mid v_n < v_m \}$$

a && b && c



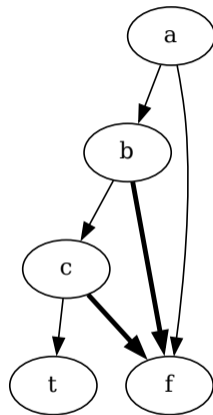
$$\{ (v_n, v_m) \in \text{Preds}(v)^2 \mid v_n < v_m \}$$

a && b && c



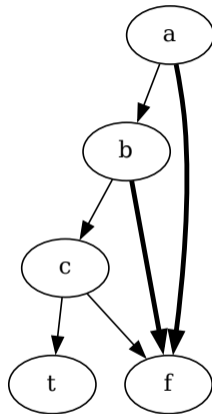
$$\{ (v_n, v_m) \in \text{Preds}(v)^2 \mid v_n < v_m \}$$

a && b && c



$$\{ (v_n, v_m) \in \text{Preds}(v)^2 \mid v_n < v_m \}$$

a && b && c



Remember

$$N[S] = \bigcup \{ \text{Succ}(v) \mid v \in S \}$$

$$N(S) = O_S$$

Implication

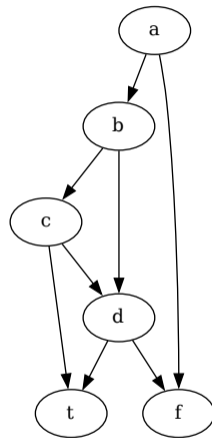
$$\text{Succs}(v_k) \subset S_n \Rightarrow S_{n+1} = S_n \cup \{v_k\}$$

$$S_0 = O_S$$

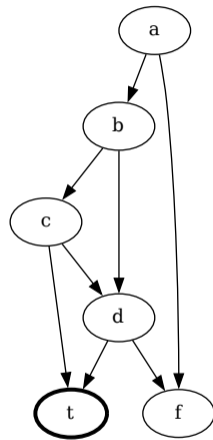
$$S = S^f - S_0$$

where S^f is the fixed point $S_{n+1} = S_n$

A && ((B && C) || D)



A && ((B && C) || D)

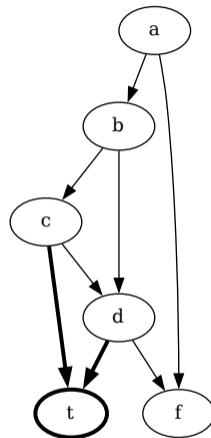


`A && ((B && C) || D)`

(c, t) short circuits

(d, t) masks

$c < d$



$A \ \&\& \ ((B \ \&\& \ C) \ || \ D)$

	(c, t)	short circuits
	(d, t)	masks
	$c < d$	

$$S_{\Omega} = c$$

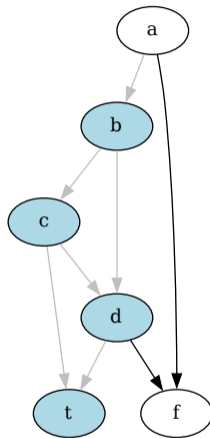
$$O_S = Succ(c) = \{d, t\}$$

$$S_0 = d, t$$

$$S_1 = S_0 + c = \{d, t, c\}$$

$$S_2 = S_1 + b = \{d, t, c, b\}$$

$$S^f = S_2$$




```

1: function MASKING-VECTOR( $B$ )
2:    $M \leftarrow \{ \}$ 
3:   for  $b$  in  $B \cup O_B$  do
4:     for  $(u, v)$  in  $\{ (u, v) \mid \text{Pred}(b)^2, u < v \}$  do
5:        $Q \leftarrow \text{QUEUE}(u)$ 
6:        $\text{MARK}(\text{Succ}(u))$ 
7:       repeat
8:          $q \leftarrow \text{POP}(Q)$ 
9:         skip if  $\text{MARKED}(\text{Succ}(q))$ 
10:         $\text{MARK}(q)$ 
11:         $\text{ADD}(M(v, b), q)$ 
12:        for  $p$  in  $\text{Pred}(q)$  do
13:          skip if  $\neg \text{IS-CONDITIONAL}(p)$ 
14:          skip if  $\text{IS-BACK-EDGE}(q, p)$ 
15:          skip if  $\text{MARKED}(p)$ 
16:          skip if  $p \notin B$ 
17:           $\text{ENQUEUE}(Q, p)$ 
18:        until  $\text{EMPTY}(Q)$ 
19:   return  $M$ 

```

Act III: Instrumentation

Instrumentation must be fast

Remember

There is an ordering $v_n < v_m$ if v_n is a left operand and v_m is a right operand in the same expression

Implication

We can sort B

Implication

There is a bijection $f : B \rightarrow \mathbb{N}$

Global accumulators

true

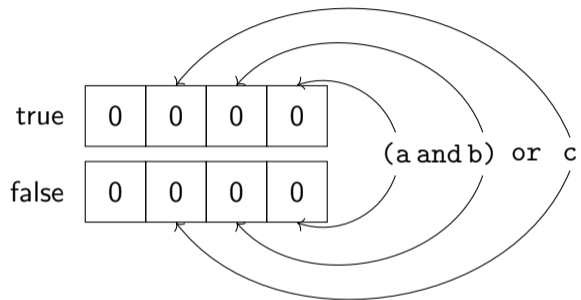
0	0	0	0
---	---	---	---

false

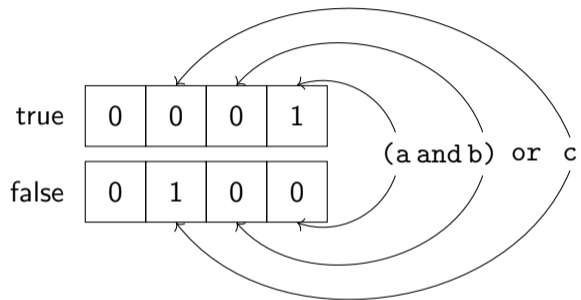
0	0	0	0
---	---	---	---

(a and b) or c

Global accumulators

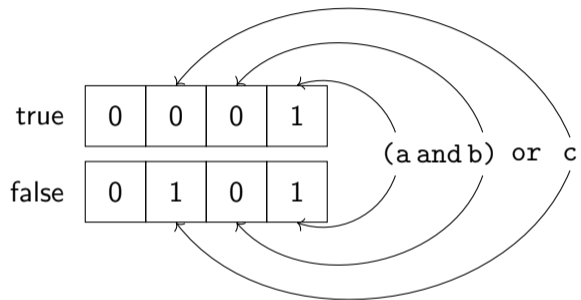


Global accumulators



f 0 0 1

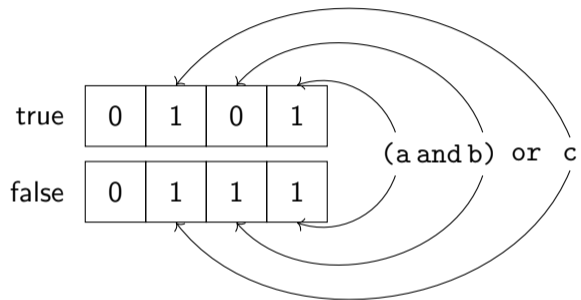
Global accumulators



f 0 0 1

f 0 0 0

Global accumulators



```
f 0 0 1  
f 0 0 0  
f 1 0 0
```

Local accumulators

$$acc \leftarrow acc \cup B(E(u, v))$$

$$acc \leftarrow acc \cap M(E(u, v))$$

where $E(u, v)$ is the edge taken and $M(E)$ are nodes masked for E

Remember

There is bijection $f : B \rightarrow \mathbb{N}$

a || b

_prelude_fn:

 _t = {0}

 _f = {0}

_a:

 if (a)

 _t |= 0x01

 goto _T

 else

 _f |= 0x01

 goto _b

_b:

 if (b)

 _t &= 0x01

 _f &= 0x01

 _t |= 0x02

 goto _T

 else

 _f |= 0x02

 goto _F

_T:

 goto _E

_F:

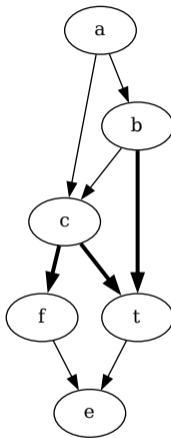
 goto _E

_E:

 _fn_t |= _t

 _fn_f |= _f

Local accumulators are flushed (bitwise-or)
on edge-to-outcome



Thank you

Me

Who Jørgen Kvalsvik

How <j@lambda.is>

Where Woven by Toyota in Tokyo,
Japan

Resources

Hayhurst (2001) A Practical Tutorial on
Modified Condition/ Decision
Coverage.

Chilenski (2001) An Investigation of Three
Forms of the Modified
Condition Decision Coverage
(MCDC) Criterion.